

# 1 Rolling Polyhedra on Tessellations

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## 22 — Abstract —

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23 We study the possible moves and reachable space by *rolling* a 3D convex polyhedron on a 2D periodic  
24 tessellation in the  $xy$ -plane, where at every step a face of the polyhedron must coincide exactly with  
25 a tile of the tessellation it rests upon. We topple the polyhedron around one of the edges of the  
26 grounded face toward a neighboring face until it hits the  $xy$ -plane on a neighboring tile, only if the  
27 new face and the new tile also coincide. We observe the space that can be reached by succession of  
28 such rolling moves. If the whole plane can be reached, we call the polyhedron a  *plane roller* for  
29 the given tessellation. We further classify polyhedra that only reach a limited strip or a bounded  
30 area on given tessellations as  *band rollers* and  *bounded rollers* respectively. We present a  
31 polynomial-time algorithm to determine the set of tiles reachable from a given starting position,  
32 which in particular determines the roller type of the given polyhedron and periodic tessellation.  
33 Using this algorithm, we compute the reachability for every regular-faced convex polyhedron on any  
34 regular-tiled ( $\leq 4$ )-uniform tessellation. Finally, we suggest how to employ these findings in puzzle  
35 games.

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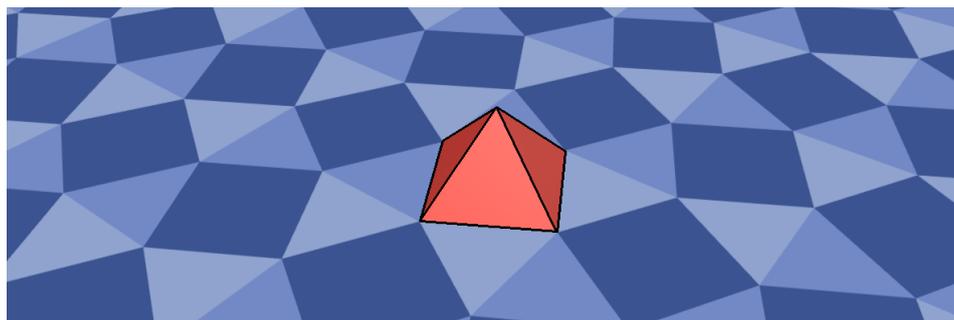


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## 1 Introduction

44

45 When it comes to rolling a polyhedron, the cube has a monopoly in term of shape representation.  
 46 *Dice rolling* puzzles feature a cube rolling around on the square grid. The goal is often to  
 47 match a given face with a given tile. They were popularized by Martin Gardner [**g-mgsb-71**,  
 48 **g-mc-77**, **g-tt-88**], but have seldom been generalized to other polyhedra on other grids, even  
 49 though some pairings were known (see Figure 3). For perspective, rolling cubes on square  
 50 grids are featured in a variety of computer games, such as *Korodice* (Gameboy, 1990), *Super*  
 51 *Mario 64* (Nintendo 64, 1996), *Devil Dice* (Playstation, 1998), *Legacy of Kain: Soul Reaver*  
 52 (Playstation, 1999), *Legend of Zelda Oracle of Ages* (Gameboy Color, 2001), *Bombastic*  
 53 (Playstation 2, 2002), *Legend of Zelda Spirit Tracks* (Nintendo DS, 2009), *Rubek* (Windows,  
 54 2016), *Roll The Box* (Mobile, 2021), and *The Last Cube* (Windows, 2022); see Figure 1.  
 55 *HyperRogue* (Windows, 2015) on the other hand involves hexagonal and heptagonal tiles in a  
 56 hyperbolic space, and in its 2021 update, rolling tetrahedron, octahedron, or icosahedron  
 57 dice on a triangular lattice. With various constraints, these puzzles can be NP-complete  
 58 [**buchin2007rolling**, **j-dice**]; when rolling more shapes, they can be PSPACE-complete  
 59 [**buchin2012rolling**, **holzer2012complexity**].

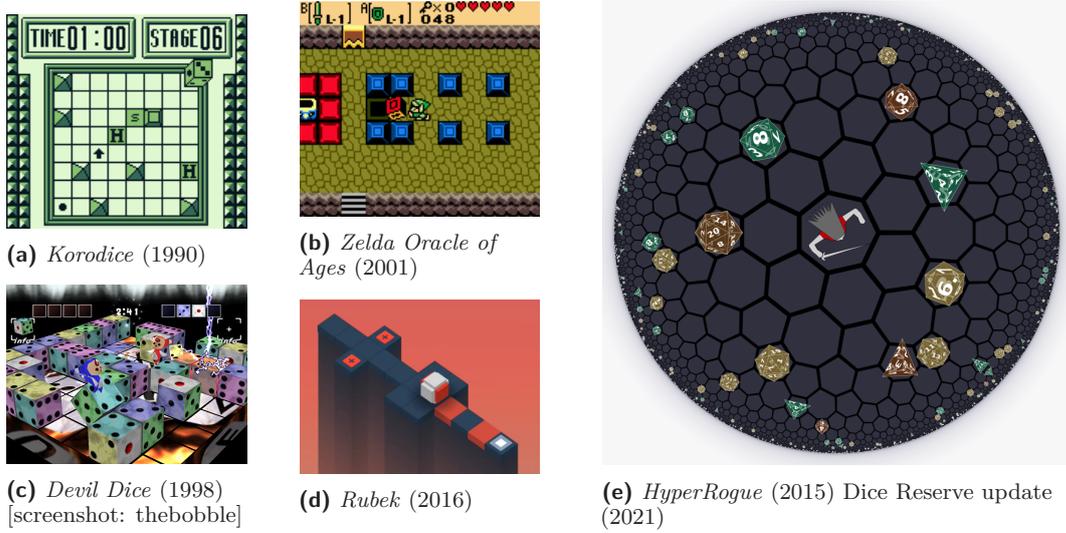
60 We formalize the concept of rolling any convex regular-faced 3D polyhedron  $P$  on any  
 61 regular-tiled periodic tessellation  $T$ , which we imagine as lying in the (horizontal)  $xy$ -plane.  
 62 Recall that a regular-faced convex polyhedron has regular polygons as faces, and that a  
 63 plane tessellation is a partition of the plane into a collection  $T$  of polygons called *tiles*  
 64 [**Grunbaum-1987**]. A regular-tiled tessellation has regular polygons as tiles. When a tile  
 65 of  $T$  is congruent to a face of  $P$ , we call them *compatible*.

66 To start, we place the polyhedron  $P$  on the tessellation so that one of its faces *rests* (i.e.,  
 67 coincides exactly) with a compatible tile. In a *rolling step*, we rotate the polyhedron about  
 68 one of the edges of its resting face, until another face rests on the tessellation. For the roll to  
 69 be *valid*, we insist that, at the end of the motion, the adjacent face of  $P$  across the rolling  
 70 edge rests on another (adjacent) compatible tile. See Figure 4 for an example.

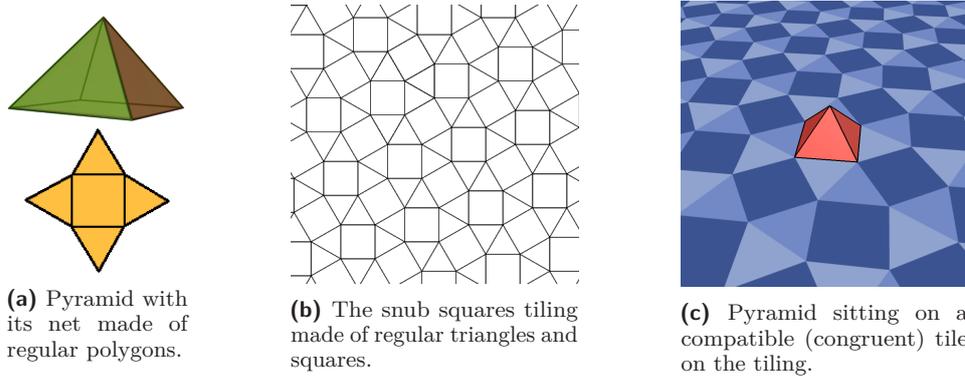
71 Valid sequences of rolls form paths in the *rolling graph* of possible configurations. If the  
 72 rolling graph contains a connected component that includes every tile of  $T$ , then we call the  
 73 polyhedron a *plane roller* for that tessellation and starting position, as it can eventually roll  
 74 to cover the entire plane.

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<sup>1</sup> Screenshot from <https://polyhedra.veille-attitude.com/>, a 3D rolling visualisation program made on the subject of this article by Rachel Aouad Albashara, Luca Insisa, Quentin Magron, Dan Ngongo, Dang Phi L Pham and Simon Yousfi for the *ULB Computer Sciences Bachelor Printemps des Sciences* showcase.



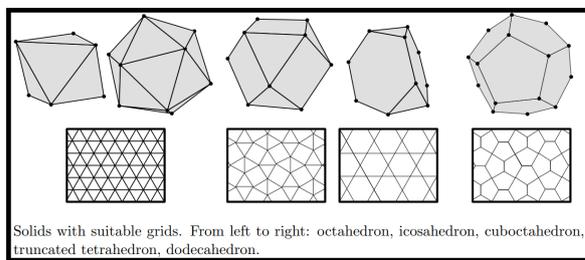
■ **Figure 1** Cube and dice-rolling puzzles in video games.



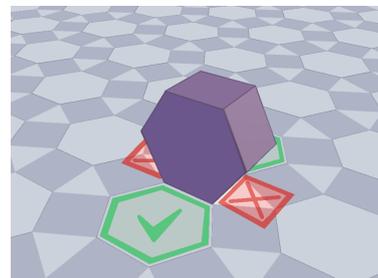
■ **Figure 2** A polyhedron and a compatible tessellation are required for rolling.

75 **1.1 Our results.**

76 In this paper, we develop a polynomial-time algorithm to identify if a polyhedron with a  
 77 periodic tessellation on a starting location is a plane roller. We essentially take advantage of

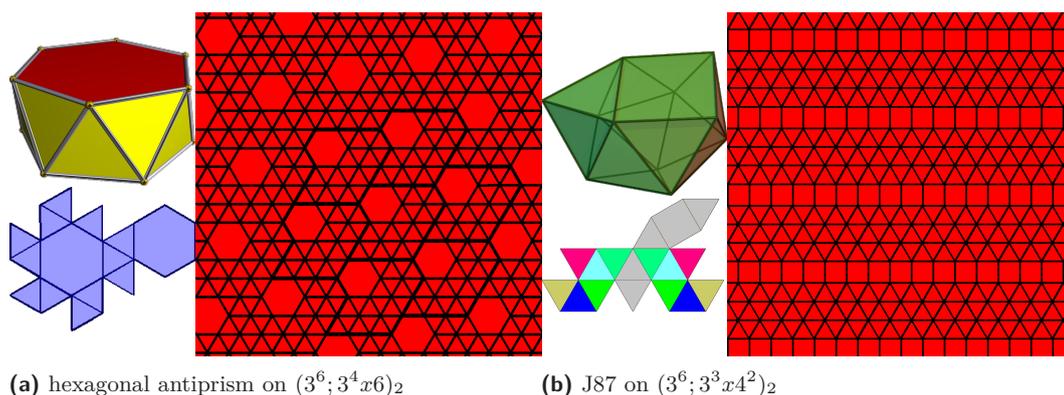


■ **Figure 3** Tiling/polyhedron pairs considered suitable for games by Buchin et al. [buchin2007rolling]



■ **Figure 4** Valid and invalid rolls. Invalid rolls are forbidden moves.

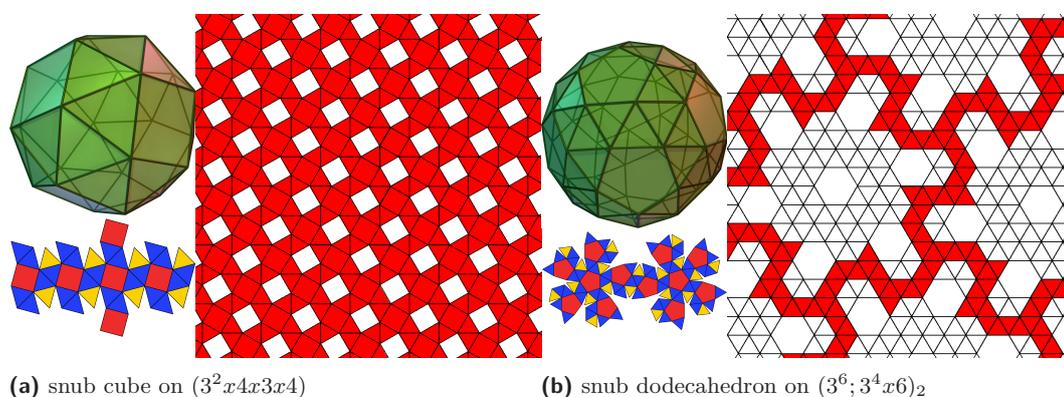
## 5:4 Rolling Polyhedra on Tessellations



(a) hexagonal antiprism on  $(3^6; 3^4 x 6)_2$

(b) J87 on  $(3^6; 3^3 x 4^2)_2$

■ **Figure 5** Examples of reachable area patterns generated by  *plane rollers* (full cover).



(a) snub cube on  $(3^2 x 4 x 3 x 4)$

(b) snub dodecahedron on  $(3^6; 3^4 x 6)_2$

■ **Figure 6** Examples of reachable area patterns generated by  *hollow-plane rollers* which leave holes in the plane.

78 the periodicity of the tessellations, coupled with the structure of the polyhedron, to prove  
79 that the resulting rolling graph also has a periodic structure that we can exploit.

80 We then apply this algorithm to completely categorize a natural finite set of interesting  
81 special cases; see Figure 11. For polyhedra, we consider the *regular-faced* convex polyhedra:  
82 the 5 Platonic solids [[euclid300BCE\\_elements](#)], 13 Archimedean solids [[field1997rediscovering](#)],  
83 92 Johnson solids and their chiral variations [[grunbaum1965faces](#), [johnson1966convex](#),  
84 [zalgaller1967convex](#)], and  $n$ -prisms and  $n$ -antiprisms where  $n \in \{3, 4, 6, 8, 10, 12\}$ , as  
85 higher-sided polygons cannot be used to tile the plane [[Grunbaum-1987](#)]. For plane  
86 tessellations, we consider all  $k$ -uniform tilings for  $k \geq 4$ , as listed in [[chavey1989tilingscatalog](#)]  
87 and defined below. Including chiral variations, this makes 129 polyhedron nets to test on 131  
88 tilings. For each case, we characterize the polyhedron rolling on the tessellation as  *plane*  
89 *rollers* which cover the whole plane,  *hollow-plane rollers* which cover a plane while leaving  
90 holes,  *band rollers* which cover an infinite band, and  *bounded rollers* which are confined  
91 to a finite area; see Figures 5,6,7,8 for several examples and Table 1 for a condensed view of  
92 the results. The most important result is the list of 145 plane roller pairs that we have found,  
93 which have uses in rolling puzzle games as alternatives to the classical cube-and-square-tiling  
94 pairing.

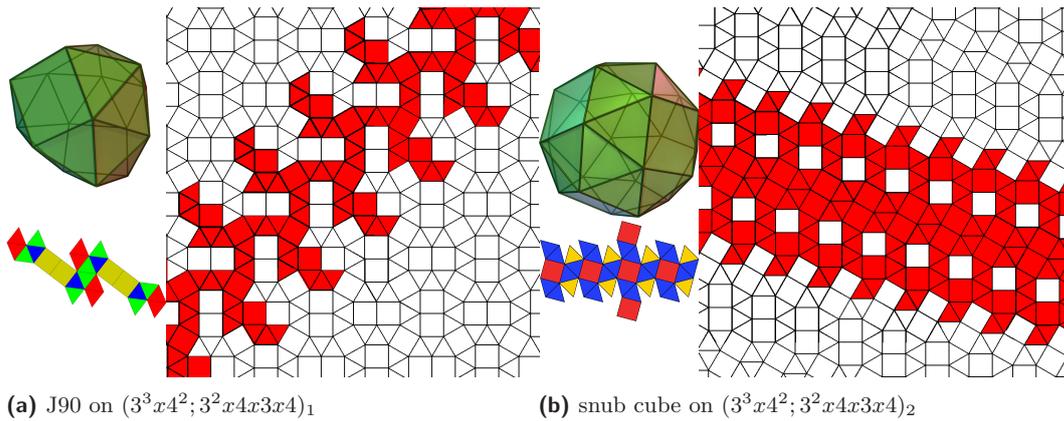


Figure 7 Examples of reachable areas patterns generated by  $\text{band rollers}$  which is stuck in an infinite band extending from the starting position.

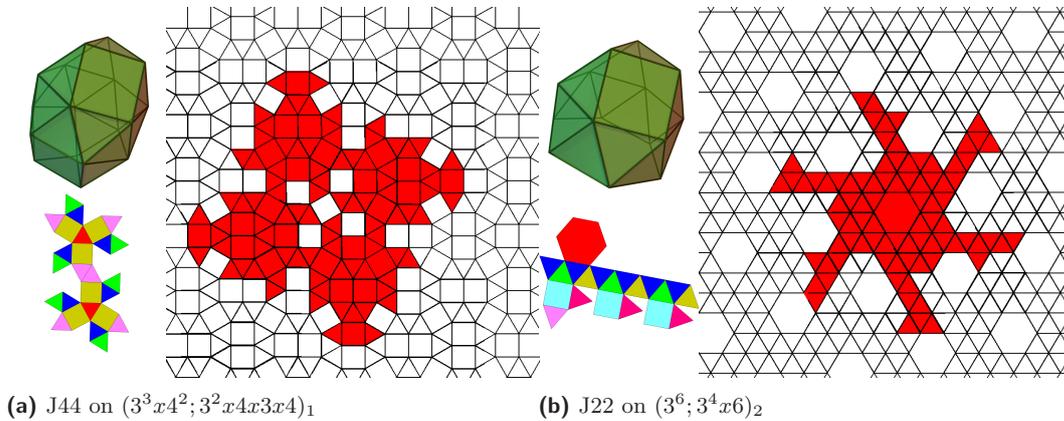
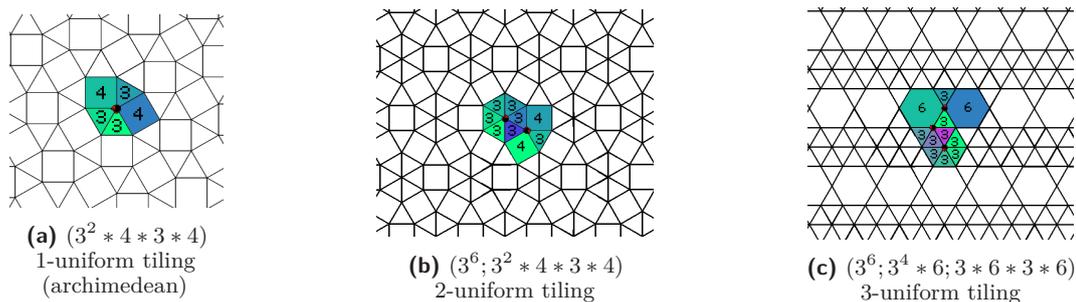


Figure 8 Examples of reachable area patterns generated by  $\text{bounded rollers}$  where the polyhedron is stuck in its starting area.

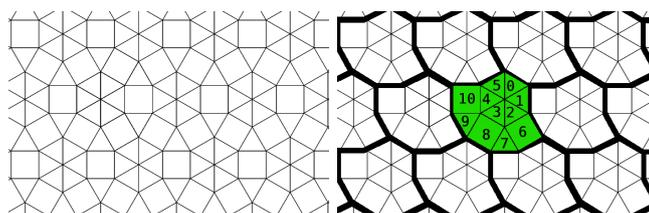
95 **1.2 Definitions**

96 As we require descriptions of regular-tiled tessellations to work with, recall that  $k$ -uniform  
 97 tilings can be defined as follows. A tiling whose polygons are aligned edge-to-edge can be  
 98 seen as a *primary graph* whose vertices are the points where tile corners join, and whose  
 99 edges are the shared edges between pairs of tiles. A *vertex type* is the clockwise cyclic order  
 100 of type of tiles (polygon shape) that surround a vertex [**chavey1989tilingscatalog**]. A  
 101 tiling that contains  $k$  orbits of vertex types that transitively describe all of its tiles through  
 102  $k$  symmetry groups is a  $k$ -isogonal tiling. If a  $k$ -isogonal tiling uses regular polygons as tiles,  
 103 then it is called  $k$ -uniform. Vertex types of  $k$ -uniform tessellations can be written as the  
 104 list of the number of sides of the regular polygons of the tiles surrounding the vertices. See  
 105 Figure 9. It is thus conventional to simply name unique  $k$ -uniform tilings by the list of their  
 106 vertex types, and overlapping names are differentiated through a subscript.

107 Working with vertex types can be unwieldy, so we also describe the tilings as explorable  
 108 graphs. All  $k$ -uniform tessellations are *periodic* on their vertices and on their faces, according  
 109 to two translational symmetries and a fundamental domain called a “supertile.” See Figure 10  
 110 for an example. A  $k$ -isogonal tiling is also  $n$ -isohedral for some  $n \geq k$  [**chavey1989tilingscatalog**]



■ **Figure 9** Examples of the naming convention of uniform tilings in the standardized “isogonal vertex type” notation, each point belonging to an orbit describing vertex types around it.



■ **Figure 10** The same tiling as Figure 9b  $(3^6; 3^2 * 4 * 3 * 4)$  in its supertile tiling representation.

111 meaning that, in the dual graph of the tiling whose nodes are tiles and edges define neighbors,  
 112 there are  $n$  orbits of tiles that transitively describe all of its tiles through  $k$  symmetry  
 113 groups [[chavey1989tilingscatalog](#)]. This means our  $k$ -uniform tessellations are formed by  
 114  $n \geq k$  transitive classes of translations, rotations, and mirror symmetries that can tile the  
 115 plane by copies of their starting tile, called *prototiles*. We can merge the prototile with its  
 116 mirror symmetry if there is one, and merge with all of its rotations if there is rotational  
 117 symmetry. (In a  $k$ -uniform tessellation, there are at most 12-wise rotations of  $30^\circ$  because  
 118 of the limitations of regular polygons.) The result is a *parallelogon supertile* that has two  
 119 translation symmetries (only) defining the tessellation [[Grunbaum-1987](#)]. In our case,  
 120 it was quicker to describe the supertiles of each tiling by hand in a homemade periodic  
 121 tessellation drawing tool, as we had no automated algorithm on hand to convert vertex-type  
 122 orbits (isohedral, edges) notations to dual-graph supertile (isogonal, tiles) notations, but we  
 123 had access to a list of  $n$ -uniform tessellation drawings on which we applied the above method.  
 124 This is why we limited ourselves to  $(\leq 4)$ -uniform tilings, which still cover 131 of the most  
 125 commonly found periodic tilings.

### 126 1.3 Related work

127 Rolling a polyhedron to cover the space in some form has been explored in [[chitour1997rolling](#)],  
 128 in term of reachability in space in [[bicchi2004reachability](#)]. We are specifically interested  
 129 in work that used the faces of the polyhedron as a base for a tessellation. Akiyama  
 130 [[akiyama2007tile](#)] defined a *frame-stamper* as a regular polyhedron that covers the whole  
 131 plane with a tiling by rolling in arbitrary directions stamping its face on the plane, and a  
 132 *tile-maker* as a polyhedron whose net developments all generate a tiling pattern. A more  
 133 relaxed definition in [[akiyama2010determination](#)] determines all *tessellation polyhedra* —  
 134 regular-faced convex polyhedra that have at least one net development that can be used to  
 135 tile the plane.

<p> Polyhedrons that Roll on a Plane on a given tessellation: (42 results for 145 pairings)</p> <p>tetrahedron with <math>(3^6)</math> – cube with <math>(4^4)</math> – octahedron with <math>(3^6)</math> – icosahedron with <math>(3^6)</math> – truncated tetrahedron with <math>(3^6; 3^2.6^2)</math> – cuboctahedron with <math>(3^2.4.3.4)</math>, <math>(3^6; 3^2.4.3.4)</math>, <math>(3^3.4^2; 3^2.4.3.4)1</math>, <math>(3^6; 3^2.4.3.4; 3^2.4.3.4)</math> – <b>j1</b> with <math>(3^2.4.3.4)</math>, <math>(3^6; 3^2.4.3.4)</math>, <math>(3^3.4^2; 3^2.4.3.4)1</math>, <math>(3^6; 3^3.4^2; 3^2.4.3.4)</math>, <math>(3^6; 3^2.4.3.4; 3^2.4.3.4)</math> – <b>j3</b> with <math>(3^6; 3^2.4.3.3.4; 3.4^2.6)</math>, <math>(3^6; 3^2.4.3.4; 3.4^2.6; 3.4.6.4)</math> – <b>j8</b> with <math>(4^4)</math>, <math>(3^6; 3^3.4^2; 4^4)1</math>, <math>(3^6; 3^3.4^2; 4^4)3</math>, <math>(3^6; 3^3.4^2; 3^2.4.3.4; 4^4)</math> – <b>j10</b> with <math>(3^6)</math>, <math>(3^6; 3^3.4^2)1</math>, <math>(3^6; 3^3.4^2)2</math>, <math>(3^6; 3^2.4.3.4)</math>, <math>(3^6; 3^3.4^2; 3^2.4.3.4)</math>, <math>(3^6; 3^6; 3^3.4^2)1</math>, <math>(3^6; 3^6; 3^3.4^2)2</math>, <math>(3^6; 3^3.4^2; 3^2.4.3.4; 4^4)</math> – <b>j11</b> with <math>(3^6)</math> – <b>j12</b> with <math>(3^6)</math> – <b>j13</b> with <math>(3^6)</math> – <b>j14</b> with <math>(3^6; 3^3.4^2)1</math> – <b>j15</b> with <math>(3^6; 3^3.4^2)1</math> – <b>j16</b> with <math>(3^6; 3^3.4^2)1</math> – <b>j17</b> with <math>(3^6)</math> – <b>j22</b> with <math>(3^6; 3^4.6)1</math>, <math>(3^6; 3^4.6; 3.6.3.6)2</math>, <math>(3^6; 3^4.6; 3.6.3.6)3</math>, <math>(3^6; 3^6; 3^4.6^2)</math> – <b>j26</b> with <math>(3^2.4.3.4)</math>, <math>(3^3.4^2; 3^2.4.3.4)2</math>, <math>(3^6; 3^2.4.3.4; 3^2.4.3.4)</math> – <b>j27</b> with <math>(3^3.4^2)</math>, <math>(3^3.4^2; 3^2.4.3.4)1</math>, <math>(3^6; 3^3.4^2; 3^2.4.3.4)</math>, <math>(3^3.4^2; 3^2.4.3.4; 3^2.4.3.4)</math> – <b>j28</b> with <math>(3^3.4^2)</math>, <math>(3^3.4^2; 4^4.4^4)1</math> – <b>j29</b> with <math>(3^2.4.3.4)</math>, <math>(3^6; 3^2.4.3.4; 3^2.4.3.4)</math> – <b>j30</b> with <math>(3^3.4^2)</math> – <b>j31</b> with <math>(3^2.4.3.4)</math>, <math>(3^6; 3^2.4.3.4; 3^2.4.3.4)</math> – <b>j37</b> with <math>(4^4)</math> – <b>j44</b> with <math>(3^6; 3^2.4.3.4; 3^2.4.3.4)</math>, <math>(3^3.4^2; 3^2.4.3.4; 3^2.4.3.4)</math> – <b>j44 chiral</b> with <math>(3^6; 3^2.4.3.4; 3^2.4.3.4)</math> – <b>j50</b> with <math>(3^6)</math>, <math>(3^6; 3^3.4^2)1</math>, <math>(3^6; 3^3.4^2)2</math>, <math>(3^6; 3^2.4.3.4)</math>, <math>(3^6; 3^6; 3^3.4^2)1</math>, <math>(3^6; 3^6; 3^3.4^2)2</math>, <math>(3^6; 3^3.4^2; 3^2.4.3.4; 4^4)</math> – <b>j51</b> with <math>(3^6)</math> – <b>j54</b> with <math>(3.4.6.4)</math> – <b>j56</b> with <math>(3.4.6.4)</math> – <b>j62</b> with <math>(3^6)</math> – <b>j65</b> with <math>(3.6.3.6)</math> – <b>j84</b> with <math>(3^6)</math> – <b>j85</b> with <math>(3^6)</math>, <math>(3^6; 3^3.4^2)1</math>, <math>(3^6; 3^3.4^2)2</math>, <math>(3^6; 3^2.4.3.4)</math>, <math>(3^6; 3^6; 3^3.4^2)1</math>, <math>(3^6; 3^6; 3^3.4^2)2</math>, <math>(3^6; 3^3.4^2; 3^3.4^2)2</math>, <math>(3^6; 3^3.4^2; 3^2.4.3.4; 4^4)</math> – <b>j86</b> with <math>(3^6)</math>, <math>(3^6; 3^3.4^2)1</math>, <math>(3^6; 3^3.4^2)2</math>, <math>(3^6; 3^2.4.3.4)</math>, <math>(3^6; 3^3.4^2; 3^2.4.3.4)</math>, <math>(3^6; 3^3.4^2; 4^4)1</math>, <math>(3^6; 3^3.4^2; 4^4)2</math>, <math>(3^6; 3^6; 3^3.4^2)1</math>, <math>(3^6; 3^3.4^2; 4^4)2</math>, <math>(3^6; 3^6; 3^3.4^2)2</math>, <math>(3^6; 3^3.4^2; 3^3.4^2)1</math>, <math>(3^6; 3^3.4^2; 3^3.4^2)2</math> – <b>j89</b> with <math>(3^6)</math>, <math>(3^6; 3^3.4^2)1</math>, <math>(3^6; 3^3.4^2)2</math>, <math>(3^6; 3^2.4.3.4)</math>, <math>(3^6; 3^3.4^2; 3^2.4.3.4)</math>, <math>(3^6; 3^3.4^2; 4^4)3</math>, <math>(3^6; 3^3.4^2; 4^4)4</math>, <math>(3^6; 3^6; 3^3.4^2)1</math>, <math>(3^6; 3^6; 3^3.4^2)2</math>, <math>(3^6; 3^3.4^2; 3^3.4^2)1</math>, <math>(3^6; 3^3.4^2; 3^3.4^2)2</math> – <b>j90</b> with <math>(3^6)</math>, <math>(3^6; 3^3.4^2)1</math>, <math>(3^6; 3^3.4^2)2</math>, <math>(3^6; 3^2.4.3.4)</math>, <math>(3^6; 3^3.4^2; 3^2.4.3.4)</math>, <math>(3^6; 3^3.4^2; 4^4)1</math>, <math>(3^6; 3^3.4^2; 4^4)2</math>, <math>(3^6; 3^6; 3^3.4^2)1</math>, <math>(3^6; 3^6; 3^3.4^2)2</math>, <math>(3^6; 3^3.4^2; 3^3.4^2)1</math>, <math>(3^6; 3^3.4^2; 3^3.4^2)2</math>, <math>(3^6; 3^2.4.3.4; 3^2.4.3.4)</math>, <math>(3^6; 3^3.4^2; 3^2.4.3.4; 4^4)</math> – <b>square antiprism</b> with <math>(3^3.4^2)</math> – <b>hexagonal antiprism</b> with <math>(3^4.6)</math>, <math>(3^6; 3^4.6)1</math>, <math>(3^6; 3^4.6)2</math>, <math>(3^4.6; 3^2.6^2)</math>, <math>(3^6; 3^4.6; 3^2.6^2)2</math>, <math>(3^6; 3^4.6; 3.6.3.6)1</math>, <math>(3^6; 3^4.6; 3.6.3.6)2</math>, <math>(3^6; 3^4.6; 3.6.3.6)3</math>, <math>(3^6; 3^6; 3^4.6^2)</math>, <math>(3^6; 3^4.6; 3^4.6)</math>, <math>(3^4.6; 3^4.6; 3.6.3.6)1</math>, <math>(3^4.6; 3^4.6; 3.6.3.6)2</math>, <math>(3^6; 3^4.6; 3^2.6^2; 3.6.3.6)</math>, <math>(3^4.6; 3^2.6^2; 3^2.6^2; 3.6.3.6)</math></p>
<p> Polyhedrons that Roll on a Hollow plane on a given tessellation: (76 results for 588 pairings)</p> <p>tetrahedron (x7) - octahedron (x7) - icosahedron (x7) - truncated tetrahedron (x12) - cuboctahedron (x4) - truncated cube - truncated octahedron (x10) - rhombicuboctahedron (x8) - truncated cuboctahedron (x6) - snub cube (x13) - snub cube chiral (x12) - truncated icosahedron (x4) - rhombicosidodecahedron (x4) - truncated icosidodecahedron (x5) - snub dodecahedron (x5) - snub dodecahedron chiral (x4) - j1 (x6) - j3 (x8) - j7 (x5) - j8 - j10 (x15) - j11 (x6) - j12 (x7) - j13 (x7) - j14 (x15) - j15 (x15) - j16 (x15) - j17 (x7) - j18 (x7) - j19 (x4) - j22 - j26 (x2) - j27 (x13) - j28 (x8) - j29 (x2) - j30 (x6) - j31 - j35 (x11) - j37 (x3) - j38 (x7) - j44 (x6) - j44 chiral (x5) - j45 (x2) - j45 chiral (x2) - j49 (x8) - j50 (x16) - j51 (x7) - j53 (x6) - j54 (x14) - j55 (x10) - j56 (x16) - j57 (x14) - j62 (x4) - j65 (x3) - j66 - j72 (x4) - j74 (x10) - j75 (x6) - j76 (x4) - j78 (x4) - j79 (x6) - j81 (x4) - j84 (x7) - j85 (x16) - j86 (x16) - j87 (x18) - j88 (x18) - j89 (x20) - j90 (x16) - triangular prism (x12) - hexagonal prism (x18) - octagonal prism - dodecagonal prism (x4) - square antiprism (x5) - hexagonal antiprism (x2) - dodecagonal antiprism (x2)</p>
<p> Polyhedrons that Roll on a Band on a given tessellation: (94 results for 2623 pairings)</p>

<p>tetrahedron (x35) - cube (x41) - octahedron (x35) - icosahedron (x35) - truncated tetrahedron (x34) - cuboctahedron (x3) - truncated octahedron (x15) - rhombicuboctahedron (x43) - snub cube (x7) - snub cube chiral (x8) - truncated icosahedron (x13) - rhombicosidodecahedron (x2) - snub dodecahedron (x7) - snub dodecahedron chiral (x7) - j1 (x7) - j3 (x2) - j7 (x43) - j8 (x39) - j9 (x42) - j10 (x29) - j11 (x31) - j12 (x35) - j13 (x35) - j14 (x42) - j15 (x42) - j16 (x42) - j17 (x35) - j18 (x43) - j19 (x41) - j20 (x42) - j21 (x42) - j22 (x30) - j23 (x30) - j24 (x30) - j25 (x30) - j26 (x7) - j27 (x17) - j28 (x46) - j29 (x4) - j30 (x15) - j31 (x3) - j35 (x44) - j36 (x49) - j37 (x46) - j38 (x44) - j39 (x47) - j40 (x42) - j41 (x42) - j42 (x42) - j43 (x42) - j44 (x32) - j44 chiral (x33) - j45 (x31) - j45 chiral (x32) - j46 (x32) - j46 chiral (x32) - j47 (x30) - j47 chiral (x30) - j48 (x30) - j48 chiral (x30) - j49 (x20) - j50 (x27) - j51 (x35) - j54 (x8) - j55 (x10) - j56 (x15) - j57 (x11) - j62 (x17) - j65 (x25) - j67 - j72 - j73 (x5) - j76 - j77 (x5) - j80 (x5) - j84 (x35) - j85 (x32) - j86 (x27) - j87 (x28) - j88 (x23) - j89 (x21) - j90 (x25) - triangular prism (x45) - pentagonal prism (x42) - hexagonal prism (x36) - octagonal prism (x42) - decagonal prism (x42) - dodecagonal prism (x43) - square antiprism (x37) - pentagonal antiprism (x30) - hexagonal antiprism (x40) - octagonal antiprism (x30) - decagonal antiprism (x30) - dodecagonal antiprism (x30)</p>
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■ **Table 1** Polyhedrons found in each Roller classification with impacted Tessellations pairing count.

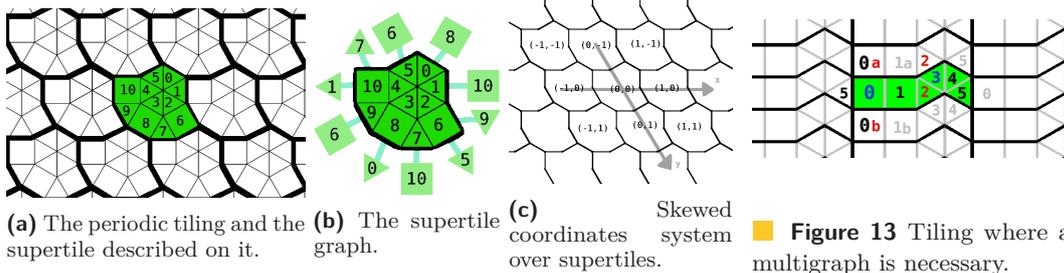


■ **Figure 11** Screenshot of the rolling pair reachable areas classification clickable web-table available at <https://akirabaes.com/polyrollly/resulttable/> in full.

137 **2 Classification algorithm**

138 **General outline:**

139 We describe a polyhedron as a dual graph (net of faces). We describe a tiling as an infinite  
 140 dual graph (tiles). We focus on periodic tilings that can be described as a repeated structure  
 141 (supertile) and a set of two coordinates. We create a looping multigraph from the supertile,  
 142 and we keep track of (i,j) the supertile coordinates when leaving its boundaries. This allows  
 143 us to more easily explore the plane. We join the polyhedron's net graph and the tessellation's  
 144 multigraph while keeping track of their relative orientation. We describe a state (f, t, o)  
 145 of the rolling graph as a face in the polyhedron's graph, a tile in the supertile graph and  
 146 their relative orientation. A position in the rolling graph is  $\langle (i, j), (f, t, o) \rangle$ . We explore a



**Figure 12** Infinite tiling to supertile multigraph **Figure 13** Tiling where a multigraph is necessary. See tiles 3 and 2.

**Figure 12** Infinite tiling to supertile multigraph

147 limited amount of steps away in a connected component of the rolling graph to find repeated  
 148 states of the connected component through the pigeonhole principle. From this as a basis,  
 149 we find the linearly independent symmetry vectors of the periodic structure of the connected  
 150 component over the rolling graph.

151 We can determine that the polyhedron/tessellation pairing is not a plane roller if we  
 152 find only zero or one linearly independent symmetry vectors. If the reachable area has two  
 153 symmetry vectors, we can determine that it is a periodic graph.

154 In a second step, we can describe the rolling graph's connected component's graph as a  
 155 repeated structure (representative area) framed by the symmetry vectors to create a smaller  
 156 looping rolling graph. We exhaustively explore the tiles of this closed graph to prove whether  
 157 or not every tile in the tessellation can be reached by rolling.

## 158 2.1 Tilings

159 There is an uncountable infinity of tilings, even when using only unit square tiles. We  
 160 restrict our attention to *periodic tilings*. These have two linearly independent translational  
 161 symmetries (say,  $\vec{a}$  and  $\vec{b}$ ) and can be described by a *fundamental domain* for the action of  
 162 these symmetries. The fundamental domain is a connected subset of the tiles (one for each  
 163 orbit), which glued together form a *supertile*  $S$ . We denote by  $|S|$  the number of tiles in  
 164 the supertile. The supertile (and the tiles that compose it) can be repeated by the action  
 165 of the two translations to obtain the original tiling. As  $S$  tiles the plane isohedrally by  
 166 translation, its boundary can be decomposed into six pieces, denoted by  $A, B, C, \bar{A}, \bar{B}, \bar{C}$ ,  
 167 counterclockwise, where  $\bar{A}, \bar{B}$ , and  $\bar{C}$  are translations of  $A$  by the action of  $\vec{a}$ ,  $B$  by the  
 168 action of  $\vec{b}$ , and  $C$  by the action of  $\vec{b} - \vec{a}$ , respectively.

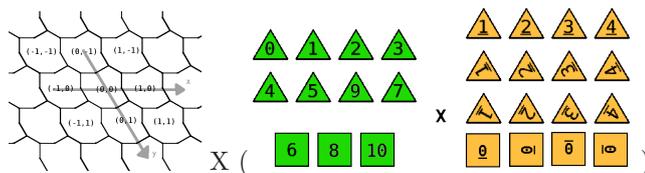
169 A copy of the supertile can be identified by its integer coordinates in the *basis* formed by  
 170 the translation vectors  $\vec{a}$  and  $\vec{b}$ . That is, the copy  $(i, j)$  corresponds to the application of the  
 171 translation  $i\vec{a} + j\vec{b}$  to  $S$ . An individual tile  $t$  of the tiling  $T$  can then be uniquely identified  
 172 by  $\langle (i, j), s \rangle$ : the coordinates  $(i, j)$  of the copy of  $S$  it is located in and its representative tile  
 173  $s$  within  $S$ .

174 A tiling  $T$  can also be represented by its (infinite) dual graph<sup>2</sup>  $G_T$ , where each tile is  
 175 a vertex of  $G_T$ , and two vertices are connected by an edge if the two corresponding tiles  
 176 are adjacent. When  $T$  is a periodic tiling, it is represented by the dual multigraph  $G_S$  of  
 177 its supertile  $S$ . For tiles touching the boundary of  $S$ , we connect them to the tiles to which  
 178 they are adjacent in the other copy or copies of the supertile, and mark the dual edges by  
 179  $A, B, C, \bar{A}, \bar{B}$ , or  $\bar{C}$  depending on the portion of the boundary they cross. The graph  $G_S$  is the

<sup>2</sup> This can be a multigraph, with parallel edges when two tiles are adjacent on more than one edge.



■ **Figure 14** Dual graph of a pyramid with information about the relative orientations of its faces.



■ **Figure 15** The rolling graph is composed of  $\langle (i, j), (tile, face, orientation) \rangle$

180 quotient of  $G_T$  by the action of the symmetries  $\vec{a}$  and  $\vec{b}$  (also denoted  $G_T/\{\vec{a}, \vec{b}\}$ ). The graph  
 181  $G_S$  can be used to navigate the tiling  $T$  or the graph  $G_T$  by updating the representation  
 182  $\langle (i, j), s \rangle$  when moving to an adjacent tile. The tile  $s$  is updated to the adjacent tile  $s'$  in  
 183  $G_S$ , and the coordinates  $(i, j)$  need to be updated when crossing a boundary of the supertile  
 184  $S$ , using the edge marks.

## 185 2.2 Rolling graphs

186 Let  $P$  be a convex polyhedron in  $\mathbb{R}^3$ . We denote by  $|P|$  the number of faces of  $P$ . The face  
 187 structure of  $P$  can be represented by its dual graph  $G_P$  where each face of  $P$  is a vertex in  
 188  $G_P$  and two vertices are connected by an edge if the two corresponding faces of  $P$  share an  
 189 edge (Figure 14).

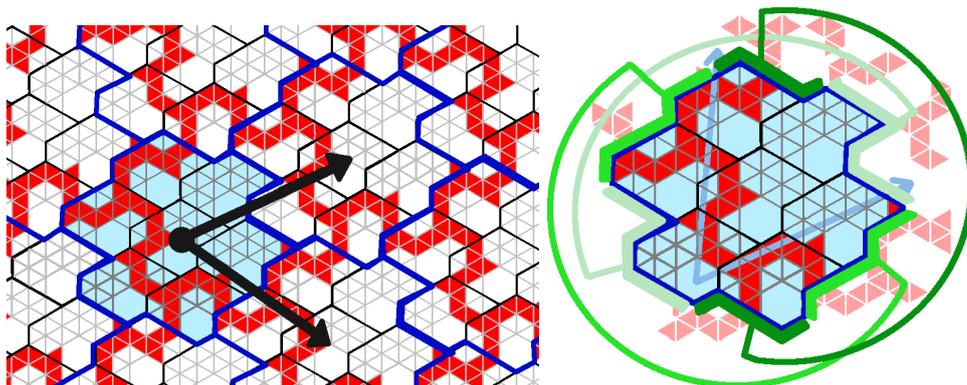
190 For a face  $f \in P$  or a tile  $t \in T$ , denote by  $|f|$  and  $|t|$  its number of edges. We number  
 191 the edges of every face  $f$  of polyhedron  $P$  counter-clockwise starting from one arbitrary edge  
 192 that will serve as the reference edge. We do the same for every tile  $t$  of the supertile  $S$  (and  
 193 the corresponding tessellation  $T$ ), with one edge being the reference edge, and the next edges  
 194 being numbered in clockwise order. A face  $f \in P$  is *compatible* with  $t \in T$  in the *orientation*  
 195  $o$  if  $|f| = |t|$  and the counter-clockwise sequence of edge lengths and angles in  $f$  starting  
 196 at edge number  $o$  matches exactly the clockwise sequence of edge lengths and angles in  $t$   
 197 starting from the reference edge. This means that  $f$  can be placed in the plane with edge  
 198 number  $o$  overlapping with the reference edge of  $t$  so that the two polygons overlap perfectly.

199 We say polyhedron  $P$  *sits on the tile  $t$  in the tessellation  $T$  with its face  $f$  at orientation*  
 200  $o$  if  $f$  and  $t$  completely overlap and the edge number  $o$  of  $f$  overlaps the reference edge of  $t$ .  
 201 The *position* of  $P$  is then represented by the tuple  $\langle t, f, o \rangle$ . When  $T$  is a periodic tiling with  
 202 supertile  $S$ , and  $t = \langle (i, j), s \rangle$  for  $s \in S$ , then this position can be written as  $\langle (i, j), s, f, o \rangle$ .  
 203 The *state* associated with this position is the tuple  $\langle s, f, o \rangle$ .

204 The *rolling graph*  $G_{P,T}$  for  $P$  and  $T$  is an infinite graph whose vertex set is the set of all  
 205 possible positions  $\langle t, f, o \rangle$ , and two nodes are connected by an edge if there is a valid roll  
 206 between them. The positions adjacent to  $\langle t, f, o \rangle$  can be easily explored by using the dual  
 207 graphs of  $P$  and  $T$ . We write  $\langle t, f, o \rangle \sim \langle t', f', o' \rangle$  if the two positions are connected by a  
 208 path in the rolling graph. In that case, we say that the two positions are *reachable* from one  
 209 another.

## 210 2.3 Symmetries of rolling graphs

211 In this section, we show that any large connected subgraph of the rolling graph  $G_{P,T}$  has a  
 212 translational symmetry. We start by bounding the number  $N$  of possible states  $\langle s, f, o \rangle$  of a



**Figure 16** By finding the symmetry vectors in a connected component, we can describe a compact representation of the connected component's periodic graph (over the rolling graph).

213 rolling graph.

$$\begin{aligned}
 214 \quad N &= \sum_{s \in S} \sum_{f \in P} (\text{number of compatible orientations between } f \text{ and } s) \\
 215 \quad &\leq \sum_{s \in S} \sum_{f \in P} |f| \leq 6|S||P|. \\
 216
 \end{aligned}$$

217 Note that the rolling graph in itself has the same translational symmetries as the tiling  
 218  $T$ , because the validity conditions are the same in both positions.

219 **Fact 1.** *If  $\langle (i, j), s_0, f_0, o_0 \rangle$  has a valid roll to  $\langle (i+i_1, j+j_1), s_1, f_1, o_1 \rangle$ , then  $\langle (i', j'), s_0, f_0, o_0 \rangle$   
 220 has a valid roll to  $\langle (i' + i_0, j' + j_0), s_1, f_1, o_1 \rangle$  for all  $i', j' \in \mathbb{Z}$ .*

221 This however does not mean that the same symmetries apply to the connected components  
 222 of the rolling graph, that is,  $\langle (i, j), s_0, f_0, o_0 \rangle$  and  $\langle (i', j'), s_0, f_0, o_0 \rangle$  might not be reachable,  
 223 even if the connected components are infinite. However, the following lemma shows that if  
 224 two distinct reachable positions have the same state, then we obtain a translational symmetry  
 225 on their connected components in the rolling graph.

226 **Lemma 1.** *If  $\langle (i, j), s, f, o \rangle \sim \langle (i + u, j + v), s, f, o \rangle$  then  
 227  $\forall \langle (i', j'), s', f', o' \rangle \sim \langle (i, j), s, f, o \rangle, \langle (i', j'), s', f', o' \rangle \sim \langle (i' + u, j' + v), s', f', o' \rangle$ .*

228 *That is,  $u\vec{a} + v\vec{b}$  defines a translational symmetry on the connected component of  
 229  $\langle (i, j), s, f, o \rangle$  in the rolling graph.*

230 **Proof.** Write the path from  $\langle (i', j'), s', f', o' \rangle$  to  $\langle (i, j), s, f, o \rangle$  in the rolling graph as  $\langle (i, j), s, f, o \rangle =$   
 231  $\langle (i + i_0, j + j_0), s_0, f_0, o_0 \rangle, \dots, \langle (i + i_k, j + j_k), s_k, f_k, o_k \rangle = \langle (i', j'), s', f', o' \rangle$ . Since, by Fact 1,  
 232  $\langle (i + u + i_\ell, j + u + j_\ell), s_\ell, f_\ell, o_\ell \rangle$  to  $\langle (i + u + i_{\ell+1}, j + u + j_{\ell+1}), s_{\ell+1}, f_{\ell+1}, o_{\ell+1} \rangle$  is a valid  
 233 roll, we can construct the path  $\langle (i', j'), s', f', o' \rangle = \langle (i + i_k, j + j_k), s_k, f_k, o_k \rangle, \dots, \langle (i + i_0, j +$   
 234  $j_0), s_0, f_0, o_0 \rangle = \langle (i, j), s, f, o \rangle \sim \langle (i + u, j + v), s, f, o \rangle = \langle (i + u + i_0, j + v + j_0), s_0, f_0, o_0 \rangle, \dots, \langle (i +$   
 235  $u + i_k, j + v + j_k), s_k, f_k, o_k \rangle = \langle (i' + u, j' + v), s', f', o' \rangle$   $\blacktriangleleft$

236 **Lemma 2.** *There is an algorithm which, in  $O(|P||S|)$  time either finds a base of the  
 237 translational symmetries of the connected component of the rolling graph containing a given  
 238 position  $\langle (i, j), s, f, o \rangle$ , or decides that the connected component is of finite size.*

239 **Proof.** Run a depth first search on the rolling graph starting from  $\langle (i, j), s, f, o \rangle$ , for  $N$  steps.  
 240 If the depth first search stops, then the connected component containing  $\langle (i, j), s, f, o \rangle$  in

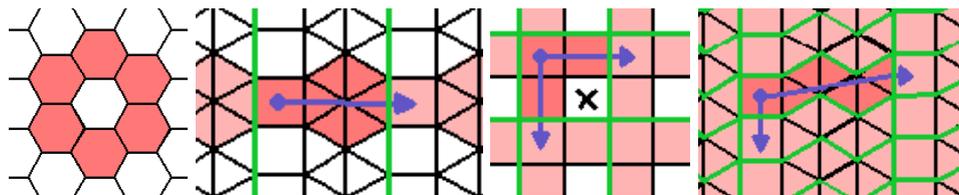
241 the rolling graph is of finite size. Otherwise, by the pigeonhole principle, we have found two  
 242 positions with the same state. By Lemma 1, we obtain a translational symmetry  $u\vec{a} + v\vec{b}$  of  
 243 the connected component.

244 Next, factor the rolling graph by this symmetry vector, that is,  $G_{P,T}/\{u\vec{a} + v\vec{b}\}$  identifies  
 245 any pair of positions  $\langle(i, j), s, f, o\rangle$  and  $\langle(i + ku, j + kv), s, f, o\rangle$  for all  $k \in \mathbb{Z}$ . Run again a  
 246 depth first search in  $G_{P,T}/\{u\vec{a} + v\vec{b}\}$  starting from  $\langle(i, j), s, f, o\rangle$ , for  $N$  steps. If the depth  
 247 first search stops, then there are only a finite number of orbits for this symmetry vector, and  
 248 so only one translational symmetry in this connected component. Otherwise, again by the  
 249 pigeonhole principle and Lemma 1, we have found a second linearly independent translational  
 250 symmetry  $u'\vec{a} + v'\vec{b}$  for this connected component. ◀

251 The algorithm in the above lemma finds a basis of two, one or zero translational symmetries  
 252 in the connected component. We can factor the rolling graph by those symmetries by  
 253 identifying symmetric tiles. As the symmetries are multiples of the supertile symmetries, this  
 254 is easily done by performing a coordinate change from the  $(i, j)$  coordinates to coordinates  
 255 in the new basis, **and a modulus operation**. When there is no symmetry, the algorithm  
 256 identifies a bounded connected component in  $G_{P,T}$ . When there is one symmetry vector,  
 257 the algorithm finds a finite number of orbits for this symmetry. Finally, when there are two  
 258 symmetry vectors in the basis, the factored rolling graph  $G_{P,T}/\{u\vec{a} + v\vec{b}, u'\vec{a} + v'\vec{b}\}$  is of size  
 259 polynomial in  $N$  and the connected component can be explored completely by depth first  
 260 search. In all three cases, a compact representation of the connected component has been  
 261 found. In the two latter cases, it takes the form of a polynomially-sized fundamental domain  
 262 and one or two translational symmetry vectors.

### 263 2.3.1 Results on reachability

264 The arguments above show how to identify the connected components in the rolling graph.  
 265 In order to find the set of tiles that can be reached from a starting position, we only need to  
 266 look at the first part  $(i, j), s$  of the positions in the connected component. Because this is a  
 267 projection, it preserves the symmetry vectors. We obtain the following classification for the  
 268 reachable area.



■ **Figure 17** No vector, one vector, two vectors but fail to cover, two vectors and full cover.

- 269 ■ If the rolling graph does not have symmetry vectors, the reachable area is bounded and  
 270  $P$  on  $T$  starting at  $\langle t, f, o\rangle$ , is a *bounded roller*.
- 271 ■ If the rolling graph only has one linearly independent vector, the reachable area is a band  
 272 and  $P$  on  $T$  starting at  $\langle t, f, o\rangle$  is a *band roller*.
- 273 ■ If the rolling graph has two linearly independent vectors, the reachable area extends  
 274 infinitely in all directions. If not every tile  $t$  is present in the reachable supertiles, the  
 275 reachable tiles forms a plane with holes and  $P$  on  $T$  starting at  $\langle t, f, o\rangle$  is a *hollow-plane*  
 276 *roller*.

277 ■ If every tile  $t$  is present in the reachable supertiles, the reachable tiles cover the entire  
 278 plane and  $P$  on  $T$  starting at  $\langle t, f, o \rangle$  is a  plane roller.

### 279 **3 Considerations for usage in puzzles**

280 To make a rolling puzzle game, we need at least: a playing area with obstacles and paths; a  
 281 polyhedron that will navigate that space; departing from a starting point; and arriving at a  
 282 goal point. The goal is often matching a specific face with a specific tile. After selecting a  
 283 polyhedron and a tessellation that have a useable reachable area pattern, we identify several  
 284 additional properties that should be tracked to facilitate puzzle design.

#### 285 **3.1 Useful properties**

##### 286 **Unused tiles in the playing area.**

287 This is determined by the     reachable area of the roller. The puzzle designer should  
 288 not put interactive elements on tiles that cannot be reached. The puzzle designer would use  
 289 the representative area and its symmetries to map out the playing space.

##### 290 **Unused faces on the polyhedron.**

291 For face-matching puzzles, determining which faces of the polyhedron are usable in the puzzle  
 292 is also important. Some faces might not be compatible with the tiling, while others might  
 293 not appear in the connected rolling graph despite being compatible. For example, puzzle  
 294 designers should avoid putting an objective marker on a polyhedron face that cannot be  
 295 rolled on. Which face was used or not is additional information that should be tracked when  
 296 computing the reachable area.

##### 297 **Guaranteed starting point: stability.**

298 In order to use a plane roller, we must know one state corresponding to the connected part  
 299 of the rolling graph that covers the plane. By starting from the wrong state (wrong face or  
 300 orientation), we might not be in a component that is connected to the one that covers the  
 301 whole plane. For some rollers, some tiles are guaranteed to belong to the largest component  
 302 for every compatible state on which we start. We can track and mark those tiles while  
 303 computing the reachable area, as those tiles can serve as starting positions to ensure that our  
 304 polyhedron will roll the plane. We call this property *tile stability*. Puzzle designers should  
 305 put the starting position of the polyhedron on a stable tile to guarantee plane coverage.

306 ► **Definition 3.** A plane roller pair  $(P, T)$  is stable on a tile  $t \in T$  if

$$307 \quad \forall f \in P \quad s.t. \quad |f| = |t|, \quad \forall o \in f : P, T \text{ on } \langle t, f, o \rangle \text{ is a roller.} \quad (1)$$

308 ► **Definition 4.** The reachable area  $RA$  for a rolling pair  $P, T$  is stable on a tile  $t \in T$  if

$$309 \quad \forall f \in P \quad s.t. \quad |f| = |t|, \quad \forall o \in f : \forall t_i \in RA : \exists f_i, o_i \quad s.t. \quad \langle t, f, o \rangle \sim \langle t_i, f_i, o_i \rangle \quad (2)$$

##### 310 **Which face reaches which tile: face-completeness.**

311 In a face-matching rolling puzzle game, the objective is to reach a specific tile with a specific  
 312 face on the polyhedron (often marked by a different color). In some cases, not every face of a  
 313 particular shape can reach every tile. When using a polyhedron/tiling pair in a puzzle game,

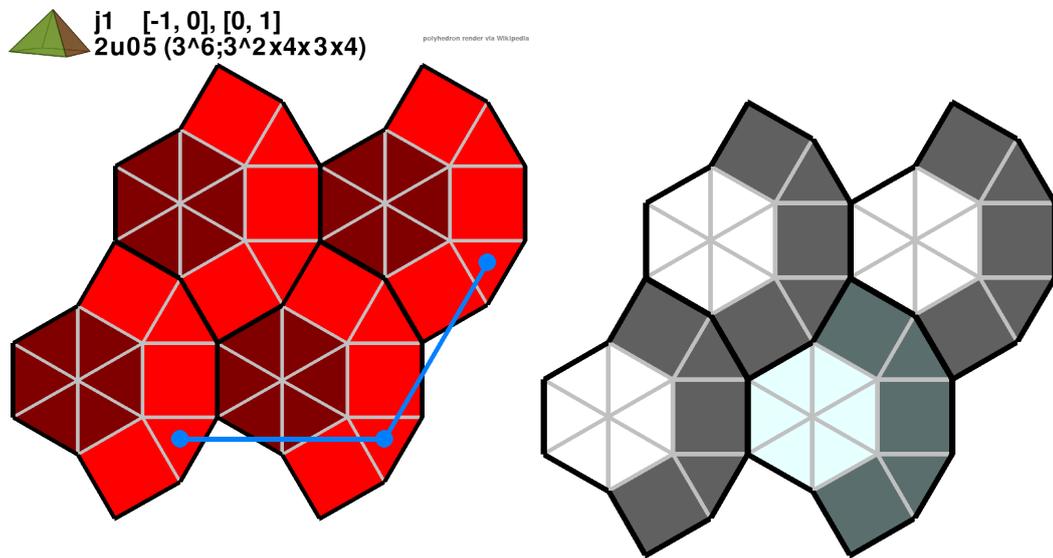
314 it can help to know which face can reach which tile. We can track specific tiles that can be  
 315 reached by every compatible face during our computations. We call those tiles face-complete  
 316 tiles. Refer to Figure 18.

317 ► **Definition 5** (face-complete tile). A roller for  $P$  on  $T$  at  $\langle t_0, f_0, o_0 \rangle$  has a face-complete  
 318 tile  $t \in T$  iff all compatible faces of the polyhedron can roll on  $t$  with some orientation, that  
 319 is,  $\forall f \text{ s.t. } |t| = |f| : \exists o \text{ s.t. } \langle t, f, o \rangle \sim \langle t_0, f_0, o_0 \rangle$ .

320 ► **Definition 6** (face-orientation-complete tile). A face-orientation-complete tile is one that  
 321 can be visited with all compatible faces in every orientation within a connected component.

### 3.2 Puzzlemaker's reference image

323 We combined all the above results in one image as a reference point for puzzlemakers. This  
 324 allows to select a tessellation/polyhedron pair very easily depending on the puzzle's needs.



■ **Figure 18** Left: face-completeness graph. In brown: face-complete tiles. In red: face-orientation-complete. Right: Stability graph with stable tiles in grey.

## 325 4 Implementation

326 The algorithm was implemented in Python 3.8 and is available on GitHub at <https://github.com/akirbaes/RollingPolyhedron/blob/master/RollingProof.py>. It uses NumPy and  
327 SymPy for creating a minimal linearly independent base, and pygame to produce images.  
328

329 The implemented version performs further manipulations, such as aggregating connected  
330 rolling graph states grouped by supertile into superstates, to lower processing time and avoid  
331 dealing with individual tile positions calculations by only looking at the supertile cartesian  
332 coordinates.

333 The result table can be consulted at <https://akirbaes.com/polyrolly/resulttable/>.

## 334 5 Limitations

335 It is left to prove for the 87 polyhedrons out of the 129 considered that did not generate  
336 a plane roller with the 131 considered tilings, if there doesn't exist a tiling on which they  
337 would be able to roll on the 2D plane.

dodecahedron, truncated cube, truncated octahedron, rhombicuboctahedron,  
truncated cuboctahedron, snub cube, snub cube c, icosidodecahedron, truncated dodecahedron,  
truncated icosahedron, rhombicosidodecahedron, truncated icosidodecahedron, snub dodecahedron,  
snub dodecahedron c, j2, j4, j5, j6, j7, j9, j18, j19, j20, j21, j23, j24, j25, j32, j33, j34, j35, j36,  
j38, j39, j40, j41, j42, j43, j45, j45 c, j46, j46 c, j47, j47 c, j48, j48 c, j49, j52, j53, j55, j57,  
j58, j59, j60, j61, j63, j64, j66, j67, j68, j69, j70, j71, j72, j73, j74, j75, j76, j77, j78, j79, j80,  
j81, j82, j83, j91, j92, triangular prism, pentagonal prism, hexagonal prism, octagonal prism,  
decagonal prism, dodecagonal prism, pentagonal antiprism, octagonal antiprism, decagonal antiprism,  
dodecagonal antiprism

■ **Table 2** Considered polyhedrons which did not generate a plane roller with considered tilings

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344 Renders of prisms and antiprisms must be attributed to Stella software as per license. Other  
345 polyhedron renders from Wikimedia Commons are to be attributed to their respective  
346 creators.